

An Approach to Formalize Information-theoretic Security of Multiparty Computation Protocols Across Cryptographic Paradigms

Cheng-Hui Weng¹, Reynald Affeldt², Jacques Garrigue³, Takafumi Saikawa³

¹Nagoya University and Mercari Inc. weng.cheng.hui.c4@math.nagoya-u.ac.jp

²National Institute of Advanced Industrial Science and Technology

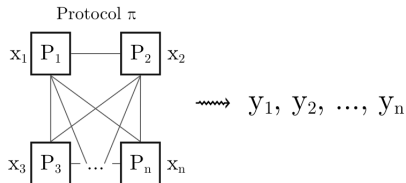
³Nagoya University

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Background: Secure-Multiparty Computation

Secure-multiparty computation (hereafter, SMC) refers to a n parties cryptographic protocol that implements an n -ary function F securely:

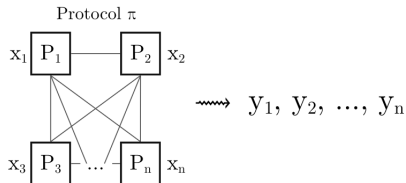
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Example: The SMC Scalar Product Protocol (SMC-SPP) [Du and Zhan(2002)]

P_a and P_b each has a private vector, and they want to compute $F = \cdot$ (scalar product) collaboratively :

$$\begin{array}{ll} P_a : \vec{x}_a \rightarrow y_a & \text{where } x_a \cdot x_b = \vec{y}_a + \vec{y}_b \\ P_b : \vec{x}_b \rightarrow y_b & P_a \text{ cannot guess } x_b, \text{ and} \\ & P_b \text{ cannot guess } x_a \end{array}$$

The Security Guarantees of SMC Protocols

SMC protocols are described in the literature in various ways:

- ① **Pseudocode and natural language:** when describing the protocol
- ② **Mathematical language:** when providing proofs for security
- ③ **Programming language:** when implementing the protocol

We want to provide a better integration to improve security.

- ① **Our Approach:** Formalization using Interpretation
- ② **Correctness using Interpretation**
- ③ **Privacy using Interpretation**
- ④ **Use-case 1:** SMC Scalar Product Protocol (SMC-SPP)
- ⑤ **Use-case 2:** Distributed and Secure Dot-Product (SMC-DSDP)
- ⑥ **Conclusion and Future Work**

Our Tool: ROCQ prover



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And the ROCQ typechecker assures that the proof contains no mistake.

Our Approach: Formalization using Interpretation

In ROCQ, we introduce a sublanguage of π -calculus to describe SMC protocols as programs:

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```
Inductive proc : Type :=  
  | Init of data & proc      (* Register input to trace *)  
  | Send of  $\mathbb{N}$  & data & proc  (* Send to nth process *)  
  | Recv of  $\mathbb{N}$  & (data  $\rightarrow$  proc) (* Receive from nth process *)  
  | Ret  of data             (* Return result *)  
  | Finish                    (* Finish successfully *)  
  | Fail.                    (* Finish with failure *)
```

Each protocol party is represented by one process, in type `proc`.

We later define a corresponding interpreter for execution and verification.

Interpretation according to Rewriting Rules

As in the π -calculus, in our language, computation can be described through rules rewriting a configuration:

$$\begin{array}{ccc} i : \text{Init } x. p \mid C & \xrightarrow{i \leftarrow x} & i : p \mid C \\ i : \text{Send } j \ x. p \mid j : \text{Recv } i \ f. \mid C & \xrightarrow{j \leftarrow x} & i : p \mid j : f \ x \mid C \\ i : \text{Ret } x \mid C & \xrightarrow{i \leftarrow x} & i : \text{Finish} \mid C \end{array}$$

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The actual interpretation of the SMC-SPP program is:

Fuel	11	10	9	8	7	6	5	4...2	1	0
Commodity Server	Init r_a	Init s_a	Init s_b	Send s_a	Send r_a	Send s_b	Send r_b	Finish		
Party#1	Init x_a	Recv s_a			Recv r_a	Send x_a'	Send x_b'	...	Ret y_a	Finish
Party#2	Init x_b	Init y_b	Recv s_b				Recv r_b	...	Ret y_b	Finish

The final *input traces* of each SMC-SPP process are:

$$P_c : (r_a, \overrightarrow{s_b}, \overrightarrow{s_a})$$

$$P_a : (y_a, t_a, \overrightarrow{x_b}, r_a, \overrightarrow{s_a}, \overrightarrow{x_a})$$

$$P_b : (y_b, \overrightarrow{x_a}, r_b, \overrightarrow{s_b}, y_b, \overrightarrow{x_b})$$

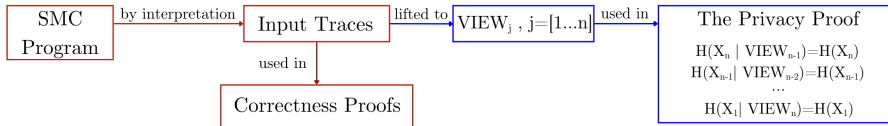
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Proofs using Interpretation

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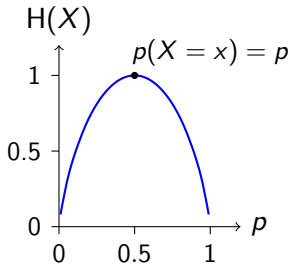


Recap: Shannon Entropy

The **Shannon entropy** $H(X)$ measures the uncertainty of a discrete random variable X with probability mass function $p(x)$:

$$H(X) = - \sum_{i=1}^n p(x_i) \log_2 p(x_i)$$

- Measures the average uncertainty (information content) of X .
- Maximum when all outcomes are equally likely.
- Minimum (zero) when X is deterministic.



Joint Random Variable, Joint Entropy and Conditional Entropy

Intuitively:

- ① Joint random variable $\langle X, Y \rangle$ is valued in X- and Y-axes.
- ② Joint entropy $H(\langle X, Y \rangle)$ is the amount of knowledge about $\langle X, Y \rangle$.
- ③ Conditional entropy $H(X | Y)$ is the amount of knowledge about X after knowing Y .

Relation: $H(X | Y) = H(\langle X, Y \rangle) - H(Y)$

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If X and Y are independent:

$$H(\langle X, Y \rangle) = H(X) + H(Y)$$

$$H(X | Y) = H(X)$$

(Knowing Y does not increase the knowledge of X)

Definition: Privacy

We follow the pen-and-paper proof work [Shen et al.(2007)] to define the privacy property of SMC protocols using *conditional entropy*:

$$H(X_i \mid \text{VIEW}_j^\pi) = H(X_i)$$

Meaning:

- 1 After the protocol π ,
- 2 The knowledge that party j gains (denoted by VIEW),
- 3 About party i 's secret X_i ,
- 4 Is equal to what party j knows before the protocol execution.

In other words: party j cannot gain any new knowledge about X_i by executing the protocol.

Use-case 1: SMC Scalar Product Protocol (SMC-SPP)

The SMC-SPP is the first use-case of our language:

The SMC Scalar Product Protocol (SMC-SPP) [Du and Zhan(2002)]

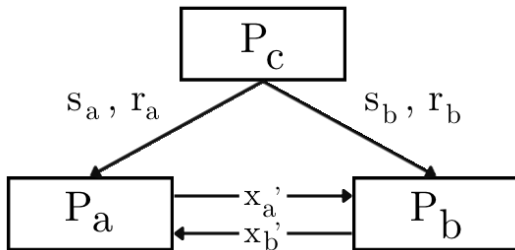
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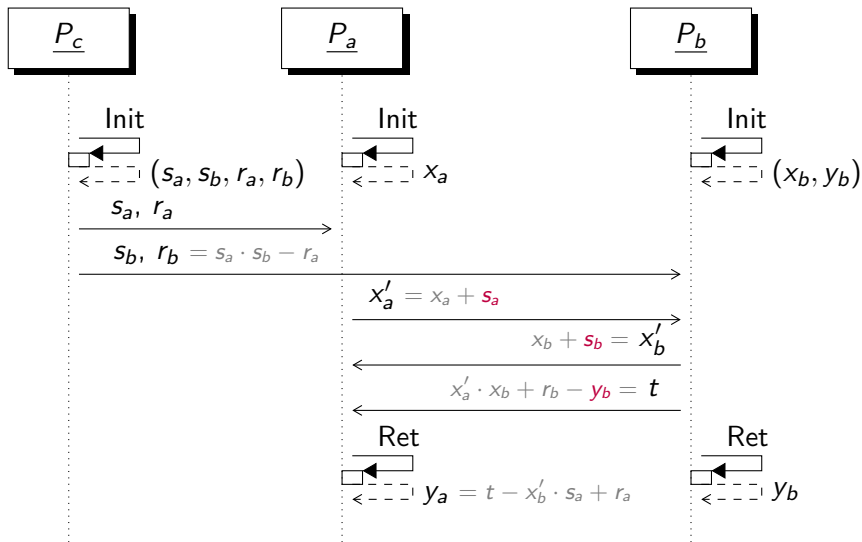
SMC-SPP was used in a real-world public health research [Chen et al.(2012)].

SMC-SPP: the Role of Each Party

The protocol has the 3rd party P_c (commodity server).
It only issues random values for the two parties:



Sequence Diagram of SMC-SPP



SMC-SPP Implementation Example: the P_a Program

P_c

P_a

P_b

Definition palice

(x_a : VX) :

proc data :=

Init (vec x_a) (

Recv_vec coserv (fun $sa \Rightarrow$

Recv_one coserv (fun $ra \Rightarrow$

Send bob (vec ($x_a + sa$))) (

Recv_vec bob (fun $xb' \Rightarrow$

Recv_one bob (fun $t \Rightarrow$

Ret (one ($t - (xb' * d\ sa) + ra$)))))))).

Proof of Correctness using Interpretation

Intermediate variables in input traces preserve how they are computed:

$$P_c : (r_a, \vec{s}_b, \vec{s}_a)$$

$$P_a : (y_a = \vec{t}_a - \vec{x}_b \cdot \vec{s}_a + r_a, \quad t_a = \vec{x}_a \cdot \vec{x}_b + r_b - y_b, \quad \vec{x}_b = \vec{x}_b + \vec{s}_b, \quad r_a, \vec{s}_a, \vec{x}_a)$$

$$P_b : (y_b, \vec{x}_a = \vec{x}_a + \vec{s}_a, \quad r_b = \vec{s}_a \cdot \vec{s}_b - r_a, \quad \vec{s}_b, y_b, \vec{x}_b)$$

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$$P_a : (y_a = \vec{t}_a - \vec{x}_b \cdot \vec{s}_a + r_a, \vec{t}_a = \vec{x}_a \cdot \vec{x}_b + r_b - y_b, \vec{x}_b = \vec{x}_b + \vec{s}_b, r_a, \vec{s}_a, \vec{x}_a)$$

$$P_b : (y_b, \vec{x}_a = \vec{x}_a + \vec{s}_a, r_b = \vec{s}_a \cdot \vec{s}_b - r_a, \vec{s}_b, y_b, \vec{x}_b)$$

Therefore, we can prove the correctness of the SMC-SPP results mostly done by the automatic ROCQ tactic `ring` in a few lines.

Theorem 1 (SMC Scalar Product)

Let $\vec{x}_a, \vec{x}_b, y_a$ and y_b be corresponding variables from `smc_scalar_product_traces`, then $\vec{x}_a \cdot \vec{x}_b = y_a + y_b$.

Because:

$$\vec{x}_a \cdot \vec{x}_b = \overbrace{\vec{x}_a \cdot \vec{x}_b + \vec{s}_a \cdot \vec{x}_b + (\vec{s}_a \cdot \vec{s}_b - r_a) - y_b - (\vec{s}_a \cdot \vec{x}_b + \vec{s}_a \cdot \vec{s}_b)}^{y_a} + r_a + y_b$$

Privacy Proof using Interpretation

We formalize the pen-and-paper proofs of the privacy-preserving property of SMC-SPP as follows:

Theorem 2 (SMC-SPP Preserves Privacy)

Let $(Y_1, T_1, \vec{X}_2', R_1, \vec{S}_1, \vec{X}_1)$ and $(Y_2, \vec{X}_1', R_2, \vec{S}_2, Y_2, \vec{X}_2)$ be party views of P_a and P_b from the lifted `smc_scalar_product_traces`, then

$$\begin{aligned} H(\vec{X}_1 \mid Y_2, \vec{X}_1', R_2, \vec{S}_2, Y_2, \vec{X}_2) &= H(\vec{X}_1) \text{ and} \\ H(\vec{X}_2 \mid Y_1, T_1, \vec{X}_2', R_1, \vec{S}_1, \vec{X}_1) &= H(\vec{X}_2). \end{aligned}$$

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Key: we need to *lift* the input traces to information-theoretic *party views*

Lifting Input Traces to Party Views

By applying the function to inputs we get input traces.

deterministic function and inputs

input traces

SMC Protocol
Program

$$\left(x_a, x_b, r_a, s_a, s_b \right) = \left((r_a, s_b, s_a), (y_a, t_a, x'_b, r_a, s_a, x_a), \right. \\ \left. (y_b, x'_a, r_b, s_b, y_b, x_b) \right)$$

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The program is lifted by composing random variables of inputs.

deterministic function and random variables

party views of random variables

SMC Protocol
Program

$$\circ \langle X_1, X_2, R_1, S_1, S_2 \rangle = \langle \langle R_1, S_2, S_1 \rangle, \langle Y_1, T_1, X'_2, R_1, S_1, X_1 \rangle, \\ \langle Y_2, X'_1, R_2, S_2, Y_2, X_2 \rangle \rangle$$

where $\langle f, g \rangle(x) = (f(x), g(x))$

Use-case 2: Distributed and Secure Dot-Product (SMC-DSDP)

We are currently formalizing this protocol using our interpretation-based approach.

- 1 SMC-DSDP [Dumas et al.(2017)] is an N -party ($N > 2$) protocol.
- 2 It utilizes homomorphic cryptographic systems.
- 3 The original work provides a security proof for the three-party case.

The Distributed and Secure Dot-Product Protocol (SMC-DSDP) [Dumas et al.(2017)]

P_a , P_b , and P_c they compute $S = u_1 \cdot v_1 + u_2 \cdot v_2 + u_3 \cdot v_3$ collaboratively:

$$P_a : (u_1, u_2, u_3, v_1, r_2, r_3) \rightarrow S$$

$$P_b : v_2 \rightarrow \beta$$

$$P_c : v_3 \rightarrow \gamma$$

where

P_a cannot guess v_2 and v_3

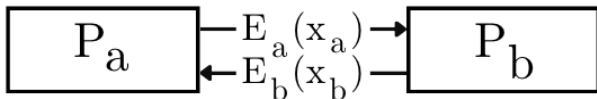
P_b cannot guess v_1 and v_3

P_c cannot guess v_1 and v_2

Security using Homomorphic Cryptographic Systems

The major difference between SMC-SPP and SMC-DSDP is how secrets are masked:

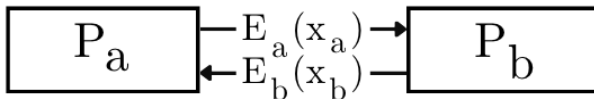
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- ① SMC-SPP: adding with uniformly distributed random values
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→ The receiver can *add* or *multiply* over the encrypted secrets without decrypting them.

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The authors distinguish *safety* from *security*:

- ① Security: parties learn only their inputs and the protocol output
- ② Safety: the protocol output does not reveal secret inputs

→ we integrate both by our method.

SMC-DSDP Security via Simulation-based Verification

Case P_a : The adversary corrupts P_a , who learns the final result $S = u_1 \cdot v_1 + u_2 \cdot v_2 + u_3 \cdot v_3$.

Security means: the adversary still cannot learn more than its own inputs and the protocol output.

SMC-DSDP Simulation-based Verification

Let

$$View_{P_a} = (U, R, \gamma, S, A, B, C)$$

denote P_a 's view of messages and γ , A , B , C are encrypted, and let

$$View_{Sim_a} = (U, R, \gamma', S, A', B', C')$$

where A' , B' , and C' are simulated and γ' is inferred from S .

If the adversary can distinguish $View_{P_a}$ from $View_{Sim_a}$, it will break the IND-CPA assumption of the cryptosystem (which is assumed impossible).

→ P_a cannot learn more than its own inputs and the output. \square

Conditional Entropy Reveals Leakage

For SMC-DSDP, privacy for V_2 requires:

$$H(V_2 \mid \text{View}_{P_a}) = H(V_2)$$

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which is generally false.

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→ However, the protocol is still *safe* even with this leakage.

Formalizing Harmless Leakage in Security Proofs

① Conditional entropy

$H(V_2 \mid \text{View}_{P_a}) < H(V_2)$ quantifies the leakage.

② Subset restriction

V_2 is restricted to the set $\{V_2 \mid (V_2, V_3) \cdot (U_2, U_3) = S\}$ for observed S , but not uniquely determined.

③ Harmless leakage

By the Rouché–Capelli theorem, if unknown variables (V_2, V_3) are more than the number of linear independent equations $((V_2, V_3) \cdot (U_2, U_3) = S)$, the system has multiple solutions; thus, the adversary cannot reconstruct the secret.

→ We are formalizing this harmless leakage by combining learn algebra and information theory.

Conclusion and Future Work

An *interpretation based methodology* combining the following ideas:

- 1 Protocol description language
- 2 Process calculus
- 3 Execution evidence from the interpretation (input traces)
- 4 Information theory

All in the same framework: from the protocol to all proofs.

Metrics: when we completed the formalization of SMC-SPP, we had:

- 1 Just 40 lines of code for defining the interpreter (reusable)
- 2 80 lemmas and theorems (57 of them are reusable)
- 3 574 lines of proof in total

(We are currently refactoring the code, so these metrics may change.)

Future work:

- 1 Complete the formalization of combining linear algebra and information theory, and complete the formalization of SMC-DSDP.



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